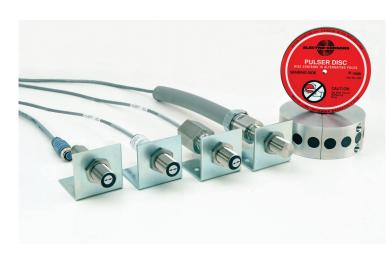


Superior • Systems • Solutions



Series 18 – Shaft Rotation Speed Sensors

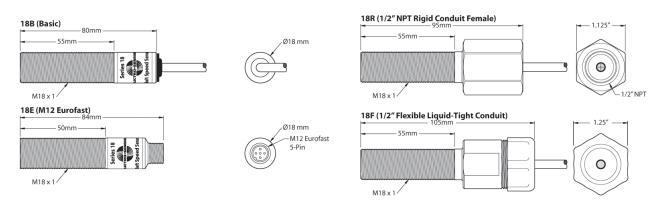
- Hall-Effect or magnetoresistive sensors available
- Single channel or quadrature signaling
- NPN or PNP transistor outputs available
- 4 Housing Options
 - Basic 18mm threaded housing
 - M12 Eurofast connector quick disconnect
 - 1/2" NPT female rigid conduit port
 - 1/2" flexible, liquid tight conduit
- Rugged, industrial-duty 18mm stainless steel sensor housing
- All sensors are epoxy potted and are liquidand dust-tight

Product Information

Description

Series 18 sensors are available in a range of output sensing and signaling options to meet even the most demanding application requirements. The sensors function by detecting passing magnets from a shaft-mounted pulser disc or wrap and output a voltage pulse frequency proportional to the shaft rotation speed. All models operate down to (and including) zero speed. Series 18 sensors are compatible with PLC inputs, tachometers and a wide range of frequency meters. All models come standard with a mounting bracket and two stainless steel hex jam nuts.

Dimensions (4 Housing Options)





Specifications • Series 18 Sensors		
Models/Options:	18Cable Length in ft (corded only; use leading zeros) O: open-collector output(s) T: terminated output(s) (internal 4.7 kΩ pull-up/down) N: npn (sinking) output(s) P: pnp (sourcing) output(s) S: single signal Q: quadrature signal (A, B; only available with Hall-Effect sensing) H: Hall-Effect sensing M: Magnetoresistive sensing B: m18x1 housing (basic) - corded E: m18x1 housing with M12 (Eurofast) connector R: m18x1 housing with ½ npt female (rigid) conduit port - corded F: m18x1 housing with ½ in (flexible) liquid-tight conduit fitting - corded	
Examples:	18BHSNO-010	(basic housing, Hall-Effect, single signal, npn, open-collector, 10ft cable)
	18EHQPT	(eurofast housing, Hall-Effect, quadrature signal, pnp, terminated)
Output Functions	Hall-Effect: Magnetoresistive: Notes:	$\begin{array}{ll} f_{pulse} = RPM * PPR / 60 & RPM = f_{pulse} * 60 / PPR \\ f_{pulse} = RPM * PPR / 30 & RPM = f_{pulse} * 30 / PPR \\ f_{pulse} \text{ is the pulse output signal frequency (Hz).} \\ RPM \text{ is the shaft revolutions-per-minute.} \\ PPR \text{ is the pulser target pulses-per-revolution} \\ (number of N/S magnet pairs or 1/2 of total magnets). \\ Magnetoresistive gives 2X the frequency of Hall-Effect. \\ Some pulser target restrictions exist for Magnetoresistive sensing (consult factory). \\ \end{array}$
Specifications	Sensor Gap V _{supply} I _{supply} (no I _{out} load) I _{out} Operating Temp Output frequency	1/4 in ±1/8 in (using pulser targets with ½" magnets) $5 \rightarrow 24$ Vdc 10 mA (max) 20 mA (max, NPN sink / PNP source) $-20 \rightarrow +85 \text{ °C} (-4 \rightarrow +185 \text{ °F})$ $0 \rightarrow 20 \text{ kHz}$
Cable	Type Color code	Shielded, 24 AWG Red (V+), Blk (Common), Wht (signal A), Grn* (signal B) * Q signal option only
M12 Euro pinout *	Specification	 Shield V+ (5 - 24Vdc) Common Signal (A) Signal (B) - Q signal option only, else unconnected * 18E housing option only

